

Stable Approximation of Stefan Problems with fully anisotropic Gibbs–Thomson Law

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Introduction

Consider a Stefan Problem for Undercooled Solidification.

Container $\Omega \subset \mathbb{R}^d$, $d = 2$ or 3 .

Solid-Liquid interface $\Gamma(t)$.

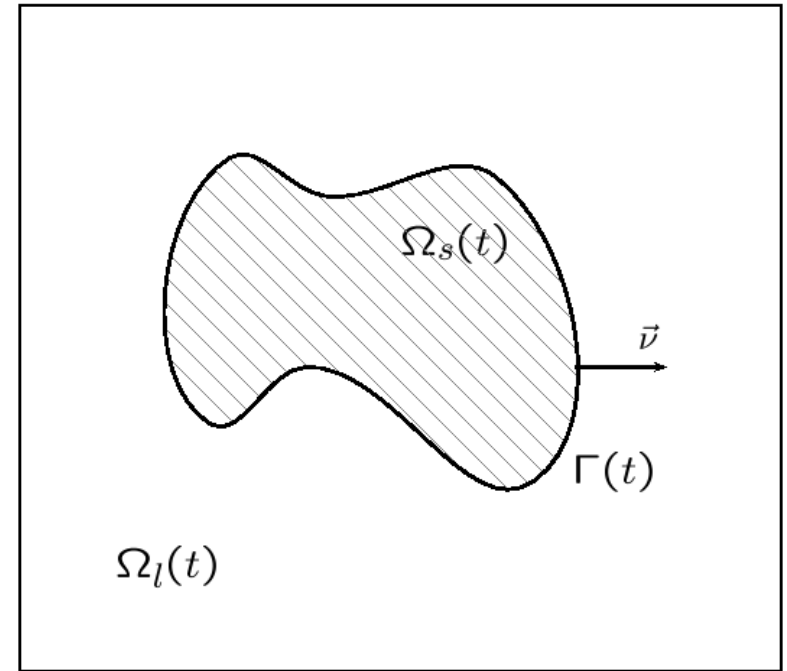
$\Omega_s(t)$, the interior of $\Gamma(t)$, is the solid region.

$\Omega_l(t) := \Omega \setminus \overline{\Omega_s(t)}$ is the liquid region.

Unit normal of $\Gamma(t)$, $\vec{\nu}$, pointing into $\Omega_l(t)$.

Let \mathcal{V} denote normal velocity of $\Gamma(t)$.

$$\left[\frac{\partial \cdot}{\partial \vec{\nu}} \right]_{\Gamma(t)} := \frac{\partial \cdot}{\partial \vec{\nu}} \Big|_{\text{liquid}} - \frac{\partial \cdot}{\partial \vec{\nu}} \Big|_{\text{solid}} .$$



Stefan Problem with Kinetic Undercooling

Find the temperature $u(\cdot, t) : \Omega \rightarrow \mathbb{R}$ and the interface $\Gamma(t) \subset \Omega$ such that for $t \in (0, T]$

$$\vartheta u_t - \Delta u = f \quad \text{in } \Omega \setminus \Gamma(t),$$

$$\left[\frac{\partial u}{\partial \vec{\nu}} \right]_{\Gamma(t)} = -\lambda \mathcal{V} \quad \text{on } \Gamma(t), \quad \text{(Stefan condition)}$$

$$\rho \mathcal{V} = \beta(\vec{\nu}) [\alpha \kappa_\gamma - a u] \quad \text{on } \Gamma(t), \quad \text{(Gibbs-Thomson condition)}$$

$$u = u_D \quad \text{on } \partial\Omega$$

with $u(\cdot, 0)$ and $\Gamma(0)$ specified.

Here $\lambda \in \mathbb{R}_{>0}$ is the latent heat, $\vartheta, \rho, \alpha \in \mathbb{R}_{\geq 0}$ and $a \in \mathbb{R}_{>0}$.

In addition, κ_γ is the weighted mean curvature of Γ , based on a given anisotropy function $\gamma(\cdot)$, and $\beta(\cdot)$ is a given anisotropic mobility.

AIM: Introduce a stable finite element approximation for the Stefan problem.

Crucial: A stable, variational formulation of κ_γ .

Anisotropic mean curvature flow

A stable approximation of the Stefan problem with

$$\rho \mathcal{V} = \beta(\vec{\nu}) [\alpha \kappa_\gamma - a u] \quad \text{on } \Gamma(t), \quad (\text{Gibbs-Thomson condition})$$

hinges on a stable numerical method for the much simpler problem

$$\mathcal{V} = \kappa_\gamma \quad \text{on } \Gamma(t), \quad (\text{MC}_\gamma)$$

i.e. motion by anisotropic mean curvature.

For simplicity, consider first the isotropic case, i.e. $\gamma(\vec{\nu}) = |\vec{\nu}| = 1$. Then $\kappa_\gamma = \kappa$ and (MC_γ) collapses to

$$\mathcal{V} = \kappa \quad \text{on } \Gamma(t), \quad (\text{MC})$$

i.e. the mean curvature flow.

On noting that $-\kappa$ can be defined as the first variation of the surface area $|\Gamma|$, (MC) is often interpreted as the L^2 -gradient flow of $|\Gamma|$.

Planar curvature flow

For simplicity, let $d = 2$. Let $\vec{x}(\rho, t)$, $\rho \in I := \mathbb{R}/\mathbb{Z}$ (periodic $[0, 1]$), be a parameterization of $\Gamma(t) \subset \mathbb{R}^2$ with unit tangent $\vec{\tau} = \vec{x}_s = \frac{\vec{x}_\rho}{|\vec{x}_\rho|}$ and curvature vector $\vec{\kappa} = \vec{\tau}_s = \vec{x}_{ss} = \frac{1}{|\vec{x}_\rho|} \left(\frac{\vec{x}_\rho}{|\vec{x}_\rho|} \right)_\rho$. It is easy to see that $\vec{x}_{ss} \cdot \vec{x}_s = 0$, and so $\vec{\kappa} = \kappa \vec{\nu}$, where κ denotes curvature and $\vec{\nu} := -\vec{x}_s^\perp$ is a chosen unit normal. (\cdot^\perp is clockwise rotation by $\frac{\pi}{2}$)

Then the first variation of

$$|\Gamma(t)| := \int_{\Gamma(t)} 1 \, ds = \int_I |\vec{x}_\rho| \, d\rho$$

can be computed as

$$\begin{aligned} \frac{d}{dt} |\Gamma(t)| &= \int_I \frac{\vec{x}_\rho}{|\vec{x}_\rho|} \cdot \vec{x}_{\rho,t} \, d\rho = - \int_I \left(\frac{\vec{x}_\rho}{|\vec{x}_\rho|} \right)_\rho \cdot \vec{x}_t \, d\rho = - \int_{\Gamma(t)} \vec{x}_{ss} \cdot \vec{x}_t \, ds \\ &= - \int_{\Gamma(t)} \kappa (\vec{x}_t \cdot \vec{\nu}) \, ds. \end{aligned}$$

Hence the L^2 -gradient flow of $|\Gamma|$ is: $\vec{x}_t \cdot \vec{\nu} = \kappa$. (MC)

Weak formulation of (MC)

Based on

$$\vec{x}_t \cdot \vec{\nu} = \kappa \quad \text{and} \quad \kappa \vec{\nu} = \vec{x}_{ss}.$$

Given $\Gamma(0)$, for $t \in (0, T]$ find $\vec{x}(t) \in \underline{V} := H^1(I; \mathbb{R}^2)$ and $\kappa(t) \in V := H^1(I; \mathbb{R})$ such that

$$\begin{aligned} \int_{\Gamma} \vec{x}_t \cdot \vec{\nu} \varphi \, ds - \int_{\Gamma} \kappa \varphi \, ds &= 0 \quad \forall \varphi \in V, \\ \int_{\Gamma} \kappa \vec{\nu} \cdot \vec{\varphi} \, ds + \int_{\Gamma} \vec{x}_s \cdot \vec{\varphi}_s \, ds &= 0 \quad \forall \vec{\varphi} \in \underline{V}. \end{aligned}$$

“Stability”: Choose $\varphi = \kappa$ and $\vec{\varphi} = \vec{x}_t$ to obtain

$$\begin{aligned} 0 &= \int_{\Gamma} \kappa^2 \, ds + \int_{\Gamma} \vec{x}_s \cdot \vec{x}_{t,s} \, ds \\ &= \int_{\Gamma} \kappa^2 \, ds + \int_I \frac{\vec{x}_{\rho}}{|\vec{x}_{\rho}|} \cdot \vec{x}_{\rho,t} \, d\rho \\ &= \int_{\Gamma} \kappa^2 \, ds + \frac{d}{dt} |\Gamma(t)|. \end{aligned}$$

Semidiscrete Finite Element Approximation

Let $I \equiv \mathbb{R}/\mathbb{Z} = \cup_{j=1}^N J_j$, $N \geq 3$, partitioned into intervals $J_j = [q_{j-1}, q_j]$.

$\underline{V}^h := \{\vec{\chi} \in C(I, \mathbb{R}^2) : \vec{\chi}|_{J_j} \text{ is linear } \forall j = 1 \rightarrow N\} =: [V^h]^2 \subset H^1(I, \mathbb{R}^2)$.

Let $\{\phi_j\}_{j=1}^N$ denote the standard basis of V^h .

$\vec{X}^h(t) \in \underline{V}^h$ approximating $\vec{x}(t) \Rightarrow$ a polygonal approximation, $\Gamma^h(t)$, to $\Gamma(t)$.

Given $\Gamma^h(0)$, for $t \in (0, T]$ find $\vec{X}^h(t) \in \underline{V}^h$ and $\kappa^h(t) \in V^h$ such that

$$\langle \vec{X}_t^h, \chi \vec{\nu}^h \rangle_{\Gamma^h}^h - \langle \kappa^h, \chi \rangle_{\Gamma^h}^h = 0 \quad \forall \chi \in V^h;$$

$$\langle \kappa^h \vec{\nu}^h, \vec{\eta} \rangle_{\Gamma^h}^h + \langle \vec{X}_s^h, \vec{\eta}_s \rangle_{\Gamma^h} = 0 \quad \forall \vec{\eta} \in \underline{V}^h;$$

where

$$\langle f, g \rangle_{\Gamma^h} := \int_{\Gamma^h(t)} f \cdot g \, ds = \int_I f \cdot g |\vec{X}_\rho^h(t)| \, d\rho$$

with $\langle \cdot, \cdot \rangle_{\Gamma^h}^h$ the mass lumped inner product.

Stability: Choose $\chi = \kappa^h$ and $\vec{\eta} = \vec{X}_t^h$ to obtain

$$0 = \langle \kappa^h, \kappa^h \rangle_{\Gamma^h}^h + \langle \vec{X}_s^h, \vec{X}_{t,s}^h \rangle_{\Gamma^h} = \langle \kappa^h, \kappa^h \rangle_{\Gamma^h}^h + \frac{d}{dt} |\Gamma^h(t)|.$$

Semi-Implicit Fully Discrete Finite Element Approximation

Let $0 = t_0 < t_1 < \dots < t_{M-1} < t_M = T$ be a partitioning of $[0, T]$, $\tau_m := t_{m+1} - t_m$, $m = 0 \rightarrow M - 1$, and $\tau := \max_{m=0 \rightarrow M-1} \tau_m$.

Given $\Gamma^0 = \vec{X}^0(I)$, $\vec{X}^0 \in \underline{V}^h$, for $m = 0 \rightarrow M - 1$ find $\vec{X}^{m+1} \in \underline{V}^h$ and $\kappa^{m+1} \in V^h$ such that

$$\left\langle \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{\nu}^m \right\rangle_{\Gamma^m}^h - \langle \kappa^{m+1}, \chi \rangle_{\Gamma^m}^h = 0 \quad \forall \chi \in V^h;$$

$$\langle \kappa^{m+1} \vec{\nu}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle \vec{X}_s^{m+1}, \vec{\eta}_s \rangle_{\Gamma^m} = 0 \quad \forall \vec{\eta} \in \underline{V}^h.$$

Stability: Choose $\chi = \kappa^{m+1}$ and $\vec{\eta} = \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}$ to obtain

$$0 = \tau_m \langle \kappa^{m+1}, \kappa^{m+1} \rangle_{\Gamma^m}^h + \langle \vec{X}_s^{m+1}, (\vec{X}^{m+1} - \vec{X}^m)_s \rangle_{\Gamma^m},$$

where, on letting $\vec{h}_j^m := \vec{X}^m(q_{j+1}) - \vec{X}^m(q_j)$,

$$\begin{aligned} \langle \vec{X}_s^{m+1}, (\vec{X}^{m+1} - \vec{X}^m)_s \rangle_{\Gamma^m} &= \sum_{j=1}^N \left[\frac{|\vec{h}_j^{m+1}|^2 - \vec{h}_j^{m+1} \cdot \vec{h}_j^m}{|\vec{h}_j^m|} \right] \\ &= \sum_{j=1}^N \left[\frac{(|\vec{h}_j^{m+1}| - |\vec{h}_j^m|)^2 + |\vec{h}_j^{m+1}| |\vec{h}_j^m| - \vec{h}_j^{m+1} \cdot \vec{h}_j^m}{|\vec{h}_j^m|} + |\vec{h}_j^{m+1}| - |\vec{h}_j^m| \right] \\ &\geq \sum_{j=1}^N [|\vec{h}_j^{m+1}| - |\vec{h}_j^m|] = |\Gamma^{m+1}| - |\Gamma^m|. \end{aligned}$$

Anisotropic Surface Energy

$$|\Gamma|_\gamma := \int_\Gamma \gamma(\vec{\nu}) \, ds$$

where $\gamma : \mathbb{R}^d \setminus \{\vec{0}\} \rightarrow \mathbb{R}_{>0}$ is a given anisotropy function, which we will assume is positively homogeneous of degree one, i.e.

$$\gamma(\lambda \vec{p}) = \lambda \gamma(\vec{p}) \quad \forall \vec{p} \in \mathbb{R}^d \setminus \{\vec{0}\}, \quad \forall \lambda \in \mathbb{R}_{>0}.$$

Let $\Gamma(\varepsilon) := \{\vec{z} + \varepsilon \vec{g}(\vec{z}) : \vec{z} \in \Gamma\}$. First variation of this energy yields

$$\frac{d}{d\varepsilon} |\Gamma(\varepsilon)|_\gamma \Big|_{\varepsilon=0} = - \int_\Gamma \vec{\kappa}_\gamma \cdot \vec{g} \, ds;$$

where

Weighted mean curvature vector: $\vec{\kappa}_\gamma := \kappa_\gamma \vec{\nu},$

Weighted mean curvature: $\kappa_\gamma := -\nabla_s \cdot \vec{\nu}_\gamma,$

Cahn–Hoffmann vector: $\vec{\nu}_\gamma := \gamma'(\vec{\nu}) \quad \text{Cahn, Hoffmann (74).}$

Planar Anisotropic Curvature Flow

In the case $d = 2$ it holds that $\kappa_\gamma \vec{\nu} = [\gamma'(\vec{\nu})]_s^\perp = [\gamma'(-\vec{x}_s^\perp)]_s^\perp$ since

$$\begin{aligned} \frac{d}{dt} |\Gamma(t)|_\gamma &= \frac{d}{dt} \int_I \gamma(-\vec{x}_\rho^\perp) d\rho = \int_I \gamma'(-\vec{x}_\rho^\perp) \cdot (-\vec{x}_{\rho,t}^\perp) d\rho = \int_I [\gamma'(-\vec{x}_s^\perp)]^\perp \cdot \vec{x}_{\rho,t} d\rho \\ &= - \int_I [\gamma'(-\vec{x}_s^\perp)]_\rho^\perp \cdot \vec{x}_t d\rho = - \int_{\Gamma(t)} [\gamma'(-\vec{x}_s^\perp)]_s^\perp \cdot \vec{x}_t ds. \end{aligned}$$

Weak formulation of

$$\mathcal{V} = \kappa_\gamma \quad \text{on } \Gamma(t) \quad (\text{MC}_\gamma)$$

is then: Given $\Gamma(0)$, for $t \in (0, T]$ find $\vec{x}(t) \in \underline{V}$ and $\kappa_\gamma(t) \in V$ such that

$$\langle \vec{x}_t, \vec{\nu} \varphi \rangle_\Gamma - \langle \kappa_\gamma, \varphi \rangle_\Gamma = 0 \quad \forall \varphi \in V,$$

$$\langle \kappa_\gamma \vec{\nu}, \vec{\varphi} \rangle_\Gamma - \langle \gamma'(\vec{\nu}), \vec{\varphi}_s^\perp \rangle_\Gamma = 0 \quad \forall \vec{\varphi} \in \underline{V}.$$

“Stability”: Choose $\varphi = \kappa_\gamma$ and $\vec{\varphi} = \vec{x}_t$ to obtain

$$0 = \langle \kappa_\gamma, \kappa_\gamma \rangle_\Gamma - \langle \gamma'(\vec{\nu}), \vec{x}_{s,t}^\perp \rangle_\Gamma = \langle \kappa_\gamma, \kappa_\gamma \rangle_\Gamma + \frac{d}{dt} |\Gamma(t)|_\gamma.$$

Semidiscrete Finite Element Approximation

Given $\Gamma^h(0)$, for $t \in (0, T]$ find $\vec{X}^h(t) \in \underline{V}^h$ and $\kappa_\gamma^h(t) \in V^h$ such that

$$\begin{aligned} \langle \vec{X}_t^h, \chi \vec{\nu}^h \rangle_{\Gamma^h}^h - \langle \kappa_\gamma^h, \chi \rangle_{\Gamma^h}^h &= 0 & \forall \chi \in V^h; \\ \langle \kappa_\gamma^h \vec{\nu}^h, \vec{\eta} \rangle_{\Gamma^h}^h - \langle \gamma'(\vec{\nu}^h), \vec{\eta}_s^\perp \rangle_{\Gamma^h} &= 0 & \forall \vec{\eta} \in \underline{V}^h. \end{aligned}$$

Stability: Choose $\chi = \kappa_\gamma^h$ and $\vec{\eta} = \vec{X}_t^h$ to obtain

$$0 = \langle \kappa_\gamma^h, \kappa_\gamma^h \rangle_{\Gamma^h}^h - \langle \gamma'(\vec{\nu}^h), [\vec{X}_{t,s}^h]^\perp \rangle_{\Gamma^h} = \langle \kappa_\gamma^h, \kappa_\gamma^h \rangle_{\Gamma^h}^h + \frac{d}{dt} |\Gamma^h(t)|_\gamma.$$

Problem: For a general anisotropy γ it does not appear possible to derive a (linear) semi-implicit fully discrete finite element approximation that mimicks this behaviour, i.e. that satisfies

$$|\Gamma^{m+1}|_\gamma + \tau_m \langle \kappa_\gamma^{m+1}, \kappa_\gamma^{m+1} \rangle_{\Gamma^m}^h \leq |\Gamma^m|_\gamma$$

and so is **unconditionally stable**.

IDEA: Restrict class of admissible anisotropies.

Example Anisotropy

As the simplest example, take the following “elliptic” anisotropy:

$$\gamma(\vec{p}) := \sqrt{\vec{p} \cdot G \vec{p}},$$

where $G \in \mathbb{R}^{2 \times 2}$ is symmetric and positive definite.

Note that

$$\gamma'(\vec{p}) = [\gamma(\vec{p})]^{-1} G \vec{p}.$$

For the semi-implicit fully discrete scheme we then approximate $\gamma'(\vec{v}^h)$ by

$$[\gamma(\vec{v}^m)]^{-1} G \vec{v}^{m+1} = -[\gamma(\vec{v}^m)]^{-1} G [\vec{X}_s^{m+1}]^\perp$$

to obtain a linear, unconditionally stable approximation.

Given $\Gamma^0 = \vec{X}^0(I)$, $\vec{X}^0 \in \underline{V}^h$, for $m = 0 \rightarrow M - 1$ find $\vec{X}^{m+1} \in \underline{V}^h$ and $\kappa_\gamma^{m+1} \in V^h$ such that

$$\left\langle \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{v}^m \right\rangle_{\Gamma^m}^h - \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h = 0 \quad \forall \chi \in V^h;$$

$$\langle \kappa_\gamma^{m+1} \vec{v}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle [\gamma(\vec{v}^m)]^{-1} G [\vec{X}_s^{m+1}]^\perp, \vec{\eta}_s^\perp \rangle_{\Gamma^m} = 0 \quad \forall \vec{\eta} \in \underline{V}^h.$$

Semi-Implicit Fully Discrete Finite Element Approximation

$$\left\langle \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{\nu}^m \right\rangle_{\Gamma^m}^h - \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h = 0 \quad \forall \chi \in V^h;$$

$$\langle \kappa_\gamma^{m+1} \vec{\nu}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle [\gamma(\vec{\nu}^m)]^{-1} G [\vec{X}_s^{m+1}]^\perp, \vec{\eta}_s^\perp \rangle_{\Gamma^m} = 0 \quad \forall \vec{\eta} \in \underline{V}^h.$$

Stability: Choose $\chi = \kappa_\gamma^{m+1}$ and $\vec{\eta} = \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}$ and observe that

$$\begin{aligned} \langle [\gamma(\vec{\nu}^m)]^{-1} G [\vec{X}_s^{m+1}]^\perp, [\vec{X}^{m+1} - \vec{X}^m]_s^\perp \rangle_{\Gamma^m} &= \sum_{j=1}^N \frac{[\vec{h}_j^{m+1}]^\perp \cdot G([\vec{h}_j^{m+1}]^\perp - [\vec{h}_j^m]^\perp)}{\gamma([\vec{h}_j^m]^\perp)} \\ &= \sum_{j=1}^N \frac{(\gamma([\vec{h}_j^{m+1}]^\perp) - \gamma([\vec{h}_j^m]^\perp))^2}{\gamma([\vec{h}_j^m]^\perp)} \\ &\quad + \sum_{j=1}^N \frac{\gamma([\vec{h}_j^{m+1}]^\perp) \gamma([\vec{h}_j^m]^\perp) - [\vec{h}_j^{m+1}]^\perp \cdot G[\vec{h}_j^m]^\perp}{\gamma([\vec{h}_j^m]^\perp)} \\ &\quad + \sum_{j=1}^N [\gamma([\vec{h}_j^{m+1}]^\perp) - \gamma([\vec{h}_j^m]^\perp)] \\ &\geq \sum_{j=1}^N [\gamma([\vec{h}_j^{m+1}]^\perp) - \gamma([\vec{h}_j^m]^\perp)] = \int_{\Gamma^{m+1}} \gamma(\vec{\nu}^{m+1}) \, ds - \int_{\Gamma^m} \gamma(\vec{\nu}^m) \, ds. \end{aligned}$$

Note: Inequality also holds element-wise.

Admissible Anisotropies

Idea: Consider an l_r -norm of such “elliptic” anisotropies.

$$\gamma(\vec{p}) = \left(\sum_{\ell=1}^L [\gamma_\ell(\vec{p})]^r \right)^{\frac{1}{r}}, \quad \gamma_\ell(\vec{p}) := \sqrt{\vec{p} \cdot G_\ell \vec{p}}, \quad r \in [1, \infty),$$

where $G_\ell \in \mathbb{R}^{2 \times 2}$, $\ell = 1 \rightarrow L$, are symmetric and positive definite.

Note that

$$\gamma'(\vec{p}) = [\gamma(\vec{p})]^{1-r} \sum_{\ell=1}^L [\gamma_\ell(\vec{p})]^{r-1} \gamma'_\ell(\vec{p}).$$

For the semi-implicit fully discrete scheme we then approximate $\gamma'(\vec{v}^h)$ by

$$\begin{aligned} & \sum_{\ell=1}^L \left[\frac{\gamma_\ell(\vec{v}^{m+1})}{\gamma(\vec{v}^{m+1})} \right]^{r-1} [\gamma_\ell(\vec{v}^m)]^{-1} G_\ell \vec{v}^{m+1} \\ &= - \sum_{\ell=1}^L \left[\frac{\gamma_\ell(\vec{v}^{m+1})}{\gamma(\vec{v}^{m+1})} \right]^{r-1} [\gamma_\ell(\vec{v}^m)]^{-1} G_\ell [\vec{X}_s^{m+1}]^\perp \end{aligned}$$

to obtain an unconditionally stable approximation that is linear for $r = 1$.

Semi-Implicit Fully Discrete Finite Element Approximation

Given $\Gamma^0 = \vec{X}^0(I)$, $\vec{X}^0 \in \underline{V}^h$, for $m = 0 \rightarrow M - 1$ find $\vec{X}^{m+1} \in \underline{V}^h$ and $\kappa_\gamma^{m+1} \in V^h$ such that

$$\left\langle \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{\nu}^m \right\rangle_{\Gamma^m}^h - \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h = 0 \quad \forall \chi \in V^h;$$

$$\langle \kappa_\gamma^{m+1} \vec{\nu}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \sum_{\ell=1}^L \left\langle \left[\frac{\gamma_\ell(\vec{\nu}^{m+1})}{\gamma(\vec{\nu}^{m+1})} \right]^{r-1} [\gamma_\ell(\vec{\nu}^m)]^{-1} G_\ell [\vec{X}_s^{m+1}]^\perp, \vec{\eta}_s^\perp \right\rangle_{\Gamma^m} = 0 \quad \forall \vec{\eta} \in \underline{V}^h.$$

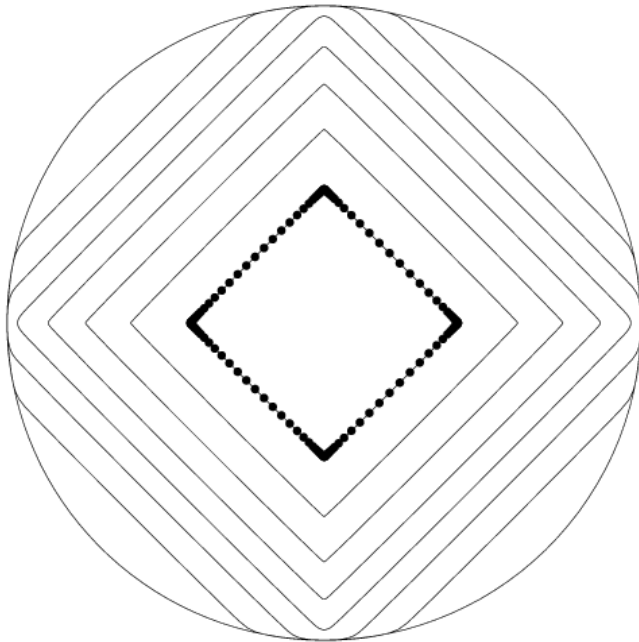
Stability: Choose $\chi = \kappa_\gamma^{m+1}$ and $\vec{\eta} = \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}$, use element-wise inequality for each γ_ℓ and apply Hölder to obtain that

$$\begin{aligned} & \sum_{\ell=1}^L \left\langle \left[\frac{\gamma_\ell(\vec{\nu}^{m+1})}{\gamma(\vec{\nu}^{m+1})} \right]^{r-1} [\gamma_\ell(\vec{\nu}^m)]^{-1} G_\ell [\vec{X}_s^{m+1}]^\perp, [\vec{X}^{m+1} - \vec{X}^m]_s^\perp \right\rangle_{\Gamma^m} \\ & \geq \sum_{\ell=1}^L \int_{\Gamma^{m+1}} \left[\frac{\gamma_\ell(\vec{\nu}^{m+1})}{\gamma(\vec{\nu}^{m+1})} \right]^{r-1} \gamma_\ell(\vec{\nu}^{m+1}) \, ds - \sum_{\ell=1}^L \int_{\Gamma^m} \left[\frac{\gamma_\ell(\vec{\nu}^{m+1})}{\gamma(\vec{\nu}^{m+1})} \right]^{r-1} \gamma_\ell(\vec{\nu}^m) \, ds \\ & \geq \int_{\Gamma^{m+1}} \sum_{\ell=1}^L \left[\frac{\gamma_\ell(\vec{\nu}^{m+1})}{\gamma(\vec{\nu}^{m+1})} \right]^r \gamma(\vec{\nu}^{m+1}) \, ds - \int_{\Gamma^m} \left(\sum_{\ell=1}^L [\gamma_\ell(\vec{\nu}^m)]^r \right)^{\frac{1}{r}} \, ds \\ & = \int_{\Gamma^{m+1}} \gamma(\vec{\nu}^{m+1}) \, ds - \int_{\Gamma^m} \gamma(\vec{\nu}^m) \, ds. \end{aligned}$$

Numerical Results for (MC_γ)

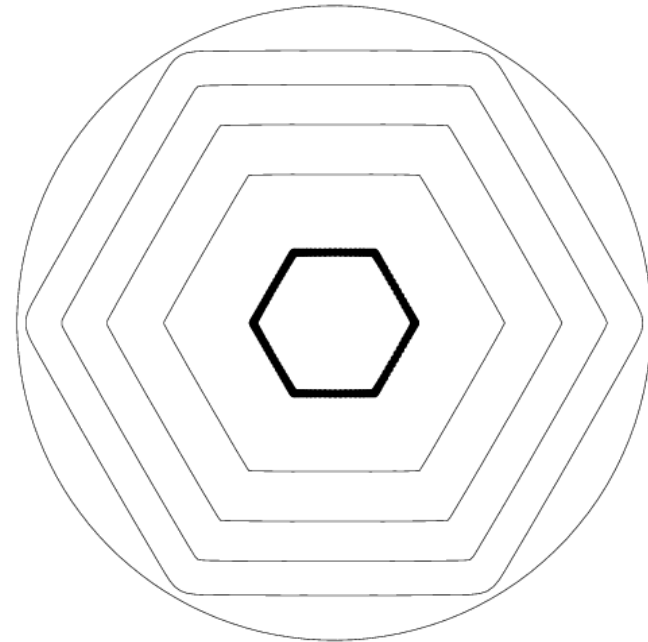
$$G_\ell := R(-\theta_\ell)D(\varepsilon_\ell)R(\theta_\ell), \quad \text{where } D(\varepsilon) := \begin{pmatrix} 1 & 0 \\ 0 & \varepsilon^2 \end{pmatrix}, \quad R(\theta) := \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

$$\varepsilon_\ell \equiv 10^{-2}, \quad (\theta_1, \dots, \theta_L) = \left(\frac{\pi}{4}, \frac{3\pi}{4}\right)$$



$$N = 128, \tau = 10^{-3}, \\ t = 0, 0.05, \dots, T = 0.35$$

$$\varepsilon_\ell \equiv 10^{-2}, \quad (\theta_1, \dots, \theta_L) = \left(0, \frac{\pi}{3}, \frac{2\pi}{3}\right)$$



$$N = 128, \tau = 10^{-3}, \\ t = 0, 0.05, \dots, T = 0.25$$

Extension to 3d

Extending the approximation from 2d to 3d is **not straightforward**.

But using ideas from differential geometry, Barrett, Garcke, Nürnberg (08) reformulated the anisotropic mean curvature κ_γ in a way that lends itself to a stable variational approximation for $d = 2$ and $d = 3$.

In particular, for

$$\gamma(\vec{p}) = \left(\sum_{\ell=1}^L [\gamma_\ell(\vec{p})]^r \right)^{\frac{1}{r}}, \quad \gamma_\ell(\vec{p}) := \sqrt{\vec{p} \cdot G_\ell \vec{p}}, \quad r \in [1, \infty),$$

where $G_\ell \in \mathbb{R}^{d \times d}$, $\ell = 1 \rightarrow L$, are symmetric and positive definite, we obtain the identity

$$\kappa_\gamma \vec{\nu} = \sum_{\ell=1}^L \gamma_\ell(\vec{\nu}) \tilde{G}_\ell \nabla_s^{\tilde{G}_\ell} \cdot \left[\left[\frac{\gamma_\ell(\vec{\nu})}{\gamma(\vec{\nu})} \right]^{r-1} \nabla_s^{\tilde{G}_\ell} \vec{x} \right].$$

Here

$$\tilde{G}_\ell := [\det G_\ell]^{\frac{1}{2}} G_\ell^{-1}, \quad \ell = 1 \rightarrow L,$$

and $\nabla_s^{\tilde{G}_\ell}$, $\nabla_s^{\tilde{G}_\ell} \cdot$ are anisotropic surface gradient and divergence operators induced by the inner product

$$(\vec{u}, \vec{v})_{\tilde{G}_\ell} := \vec{u} \cdot \tilde{G}_\ell \vec{v} \quad \forall \vec{u}, \vec{v} \in \mathbb{R}^d.$$

Parametric Finite Element Approximation

Note: In contrast to

$$\mathcal{K}_\gamma \vec{v} = -\nabla_s \cdot (\vec{v} [\gamma'(\vec{v})]^T) + \nabla_s \cdot (\gamma(\vec{v}) \nabla_s \vec{x}) - \gamma(\vec{v}) \Delta_s \vec{x},$$

which is based on the standard, isotropic differential operators, the identity

$$\mathcal{K}_\gamma \vec{v} = \sum_{\ell=1}^L \gamma_\ell(\vec{v}) \tilde{G}_\ell \nabla_s^{\tilde{G}_\ell} \cdot \left[\left[\frac{\gamma_\ell(\vec{v})}{\gamma(\vec{v})} \right]^{r-1} \nabla_s^{\tilde{G}_\ell} \vec{x} \right],$$

gives rise to a symmetric formulation. In particular, we obtain:

Find $\{\vec{X}^{m+1}, \kappa_\gamma^{m+1}\} \in \underline{V}^h(\Gamma^m) \times V^h(\Gamma^m)$ such that

$$\left\langle \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{v}^m \right\rangle_{\Gamma^m}^h - \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h = 0 \quad \forall \chi \in V^h(\Gamma^m),$$

$$\langle \kappa_\gamma^{m+1} \vec{v}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle \nabla_s^{\tilde{G}} \vec{X}^{m+1}, \nabla_s^{\tilde{G}} \vec{\eta} \rangle_{\gamma, \Gamma^m} = 0 \quad \forall \vec{\eta} \in \underline{V}^h(\Gamma^m),$$

where

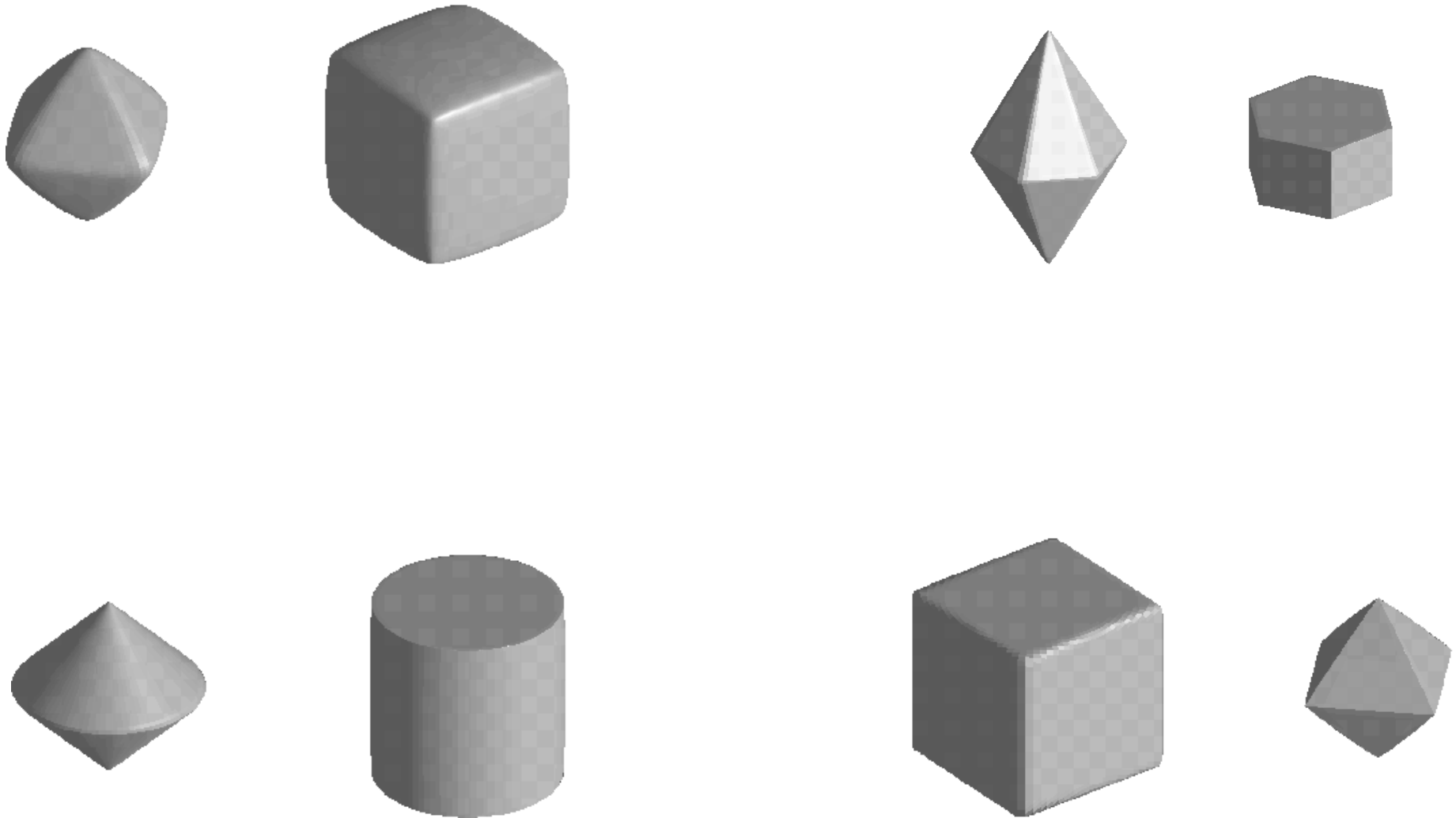
$$\langle \nabla_s^{\tilde{G}} \vec{X}^{m+1}, \nabla_s^{\tilde{G}} \vec{\eta} \rangle_{\gamma, \Gamma^m} := \sum_{\ell=1}^L \int_{\Gamma^m} \left[\frac{\gamma_\ell(\vec{v}^{m+1})}{\gamma(\vec{v}^{m+1})} \right]^{r-1} (\nabla_s^{\tilde{G}_\ell} \vec{X}^{m+1}, \nabla_s^{\tilde{G}_\ell} \vec{\eta})_{\tilde{G}_\ell} \gamma_\ell(\vec{v}^m) \, ds.$$

$r = 1$: Linear system. Existence, uniqueness and stability.

$r > 1$: Nonlinear system. Stability.

Example Anisotropies, $d = 3$

Examples of Frank diagrams \mathcal{F} and associated Wulff shapes \mathcal{W} :



Stefan Problem with Kinetic Undercooling

Find the temperature $u(\cdot, t) : \Omega \rightarrow \mathbb{R}$ and the interface $\Gamma(t) \subset \Omega$ such that for $t \in (0, T]$

$$\vartheta u_t - \Delta u = f \quad \text{in } \Omega \setminus \Gamma(t),$$

$$\left[\frac{\partial u}{\partial \vec{\nu}} \right]_{\Gamma(t)} = -\lambda \mathcal{V} \quad \text{on } \Gamma(t), \quad \text{(Stefan condition)}$$

$$\rho \mathcal{V} = \beta(\vec{\nu}) [\alpha \kappa_\gamma - a u] \quad \text{on } \Gamma(t), \quad \text{(Gibbs-Thomson condition)}$$

$$u = u_D \quad \text{on } \partial\Omega$$

with $u(\cdot, 0)$ and $\Gamma(0)$ specified.

Here $\lambda \in \mathbb{R}_{>0}$ is the latent heat, $\vartheta, \rho, \alpha \in \mathbb{R}_{\geq 0}$ and $a \in \mathbb{R}_{>0}$.

In addition, κ_γ is the weighted mean curvature of Γ , based on a given anisotropy function $\gamma(\cdot)$, and $\beta(\cdot)$ is a given anisotropic mobility.

Weak Formulation

Let $(\eta, \phi) := \int_{\Omega} \eta \phi \, d\vec{z}$. For a test function φ with $\varphi = 0$ on $\partial\Omega$, we have that

$$\vartheta(u_t, \varphi) + (\nabla u, \nabla \varphi) - (f, \varphi) = - \int_{\Gamma(t)} \left[\frac{\partial u}{\partial \vec{\nu}} \right]_{\Gamma(t)} \varphi \, ds = \lambda \int_{\Gamma(t)} (\vec{x}_t \cdot \vec{\nu}) \varphi \, ds. \quad (1)$$

Moreover

$$\rho(\vec{x}_t \cdot \vec{\nu}) = \beta(\vec{\nu}) [\alpha \kappa_\gamma - a u] \quad (2)$$

and

$$\kappa_\gamma \vec{\nu} = \sum_{\ell=1}^L \gamma_\ell(\vec{\nu}) \tilde{G}_\ell \nabla_s^{\tilde{G}_\ell} \cdot \left[\left[\frac{\gamma_\ell(\vec{\nu})}{\gamma(\vec{\nu})} \right]^{r-1} \nabla_s^{\tilde{G}_\ell} \vec{x} \right]. \quad (3)$$

Testing (1) with $\varphi = u - u_D$, (2) with $\chi = \frac{\lambda}{a} \vec{x}_t \cdot \vec{\nu}$ and (3) with $\vec{\eta} = \frac{\alpha \lambda}{a} \vec{x}_t$ yields that

$$\begin{aligned} \frac{d}{dt} \left(\frac{\vartheta}{2} |u - u_D|_{\Omega}^2 + \frac{\alpha \lambda}{a} |\Gamma(t)|_\gamma + \lambda u_D \operatorname{vol}(\Omega_s(t)) \right) + |\nabla u|_{\Omega}^2 + \frac{\lambda \rho}{a} \int_{\Gamma(t)} \frac{\nu^2}{\beta(\vec{\nu})} \, ds \\ = (f, u - u_D). \end{aligned}$$

We will directly discretize (1)–(3), resulting in a coupled system, and obtain a discrete analogue of this energy bound.

Parametric Finite Element Approximation

Based on continuous piecewise linear approximations of u , Γ and κ_γ .

For $m \geq 0$, given $U^m \in S_D^h$ and $\vec{X}^m \in \underline{V}^h(\Gamma^m)$,
find $U^{m+1} \in S_D^h$, $\vec{X}^{m+1} \in \underline{V}^h(\Gamma^m)$ and $\kappa_\gamma^{m+1} \in W^h(\Gamma^m)$ such that for all
 $\varphi \in S_0^h$, $\chi \in W^h(\Gamma^m)$, $\vec{\eta} \in \underline{V}^h(\Gamma^m)$

$$\vartheta \left(\frac{U^{m+1} - U^m}{\tau_m}, \varphi \right)^h + (\nabla U^{m+1}, \nabla \varphi) - \lambda \left\langle \pi^m \left[\frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m} \cdot \vec{\omega}^m \right], \varphi \right\rangle_{\Gamma^m} = (f^{m+1}, \varphi)^h,$$

$$\rho \left\langle [\beta(\vec{\nu}^m)]^{-1} \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{\nu}^m \right\rangle_{\Gamma^m}^h - \alpha \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h + a \langle U^{m+1}, \chi \rangle_{\Gamma^m} = 0,$$

$$\langle \kappa_\gamma^{m+1} \vec{\nu}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle \nabla_s^{\tilde{G}} \vec{X}^{m+1}, \nabla_s^{\tilde{G}} \vec{\eta} \rangle_{\gamma, \Gamma^m} = 0.$$

Coupled system of equations.

$r = 1$: Linear system. Existence, uniqueness and stability.

$r > 1$: Nonlinear system. Stability.

Stability

$$\begin{aligned} \vartheta \left(\frac{U^{m+1} - U^m}{\tau_m}, \varphi \right)^h + (\nabla U^{m+1}, \nabla \varphi) - \lambda \left\langle \pi^m \left[\frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m} \cdot \vec{\omega}^m \right], \varphi \right\rangle_{\Gamma^m} \\ = (f^{m+1}, \varphi)^h, \\ \rho \left\langle [\beta(\vec{\nu}^m)]^{-1} \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m}, \chi \vec{\omega}^m \right\rangle_{\Gamma^m}^h - \alpha \langle \kappa_\gamma^{m+1}, \chi \rangle_{\Gamma^m}^h + a \langle U^{m+1}, \chi \rangle_{\Gamma^m} = 0, \\ \langle \kappa_\gamma^{m+1} \vec{\omega}^m, \vec{\eta} \rangle_{\Gamma^m}^h + \langle \nabla_s^{\tilde{G}} \vec{X}^{m+1}, \nabla_s^{\tilde{G}} \vec{\eta} \rangle_{\gamma, \Gamma^m} = 0. \end{aligned}$$

Stability: Choose $\varphi = U^{m+1} - u_D$, $\chi = \frac{\lambda}{a} \pi^m [(\vec{X}^{m+1} - \vec{X}^m) \cdot \vec{\omega}^m]$ and $\vec{\eta} = \frac{\alpha \lambda}{a} (\vec{X}^{m+1} - \vec{X}^m)$ yields, on recalling that

$$\langle \nabla_s^{\tilde{G}} \vec{X}^{m+1}, \nabla_s^{\tilde{G}} (\vec{X}^{m+1} - \vec{X}^m) \rangle_{\gamma, \Gamma^m} \geq |\Gamma^{m+1}|_\gamma - |\Gamma^m|_\gamma,$$

that

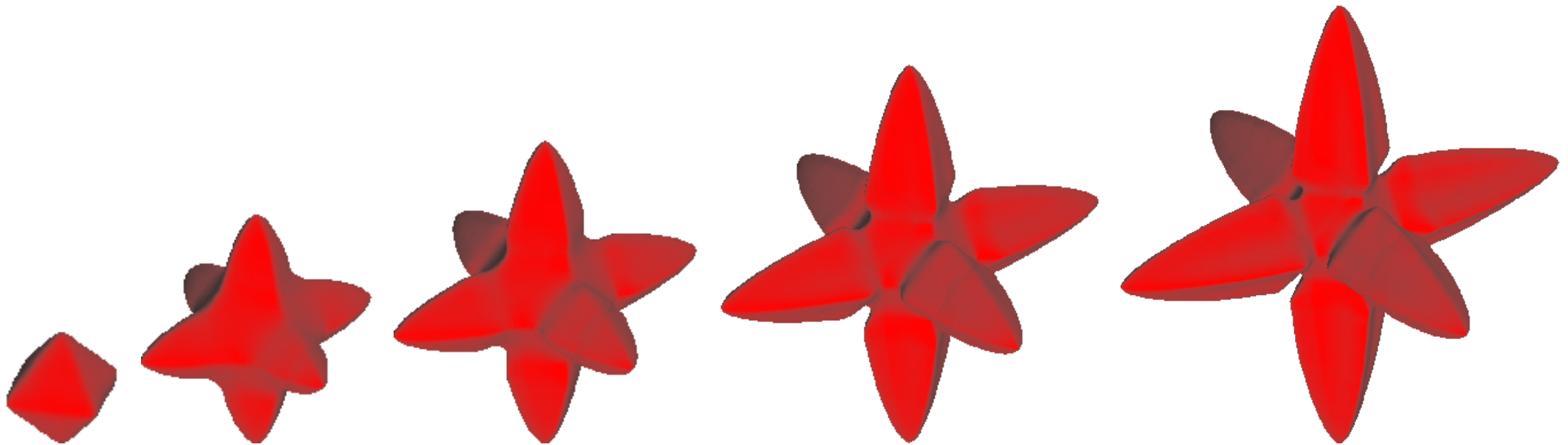
$$\begin{aligned} \mathcal{E}(U^{m+1}, \vec{X}^{m+1}) + \lambda u_D \langle \vec{X}^{m+1} - \vec{X}^m, \vec{\nu}^m \rangle_{\Gamma^m}^h + \frac{\vartheta}{2} |U^{m+1} - U^m|_{\Omega, h}^2 \\ + \tau_m |\nabla U^{m+1}|_{\Omega}^2 + \tau_m \frac{\lambda \rho}{a} \left| [\beta(\vec{\nu}^m)]^{-\frac{1}{2}} \frac{\vec{X}^{m+1} - \vec{X}^m}{\tau_m} \cdot \vec{\omega}^m \right|_{\Gamma^m, h}^2 \\ \leq \mathcal{E}(U^m, \vec{X}^m) + (f^{m+1}, U^{m+1} - u_D)^h; \end{aligned}$$

where $\mathcal{E}(U^m, \vec{X}^m) := \frac{\vartheta}{2} |U^m - u_D|_{\Omega, h}^2 + \frac{\alpha \lambda}{a} |\Gamma^m|_\gamma$.

Numerical Results

$\gamma(\vec{\nu})$ is a cubic anisotropy ($\{G_\ell\}_{\ell=1}^3$, with $r = 9$ and reg. $\varepsilon = 0.6$).

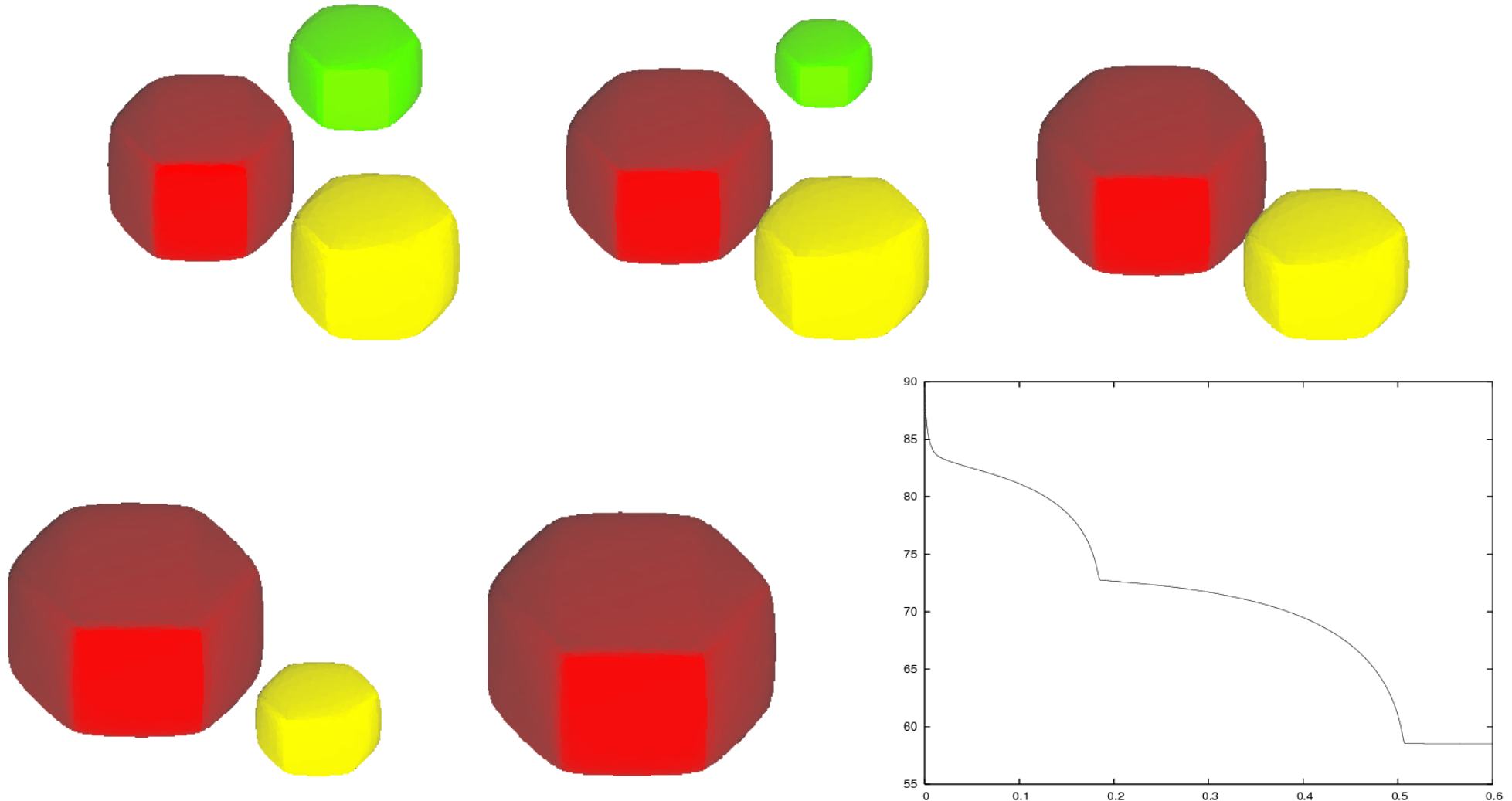
$\beta(\vec{\nu}) = \gamma(\vec{\nu})$, $u_D = -1$, $\Omega = (-4, 4)^3$, $\Gamma(0)$ sphere radius $\frac{1}{10}$.



$\vec{X}(t)$ at times $t = 0.1, 0.2, 0.25, 0.3, 0.34$.

Mesh parameters $N_f = 512$, $N_c = 32$ for Ω ,
 $J_\Gamma^0 = 768$ for Γ and uniform time step $\tau = 2 \times 10^{-4}$.

Anisotropic Mullins–Sekerka ($\vartheta = \rho = 0, \lambda = a = \alpha = 1$)



$\vec{X}(t)$ at times $t = 0.05, 0.15, 0.3, 0.45, T = 0.6$, and the energy $|\Gamma^m|$.

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