## A nonlinear cross-diffusion system for contact inhibition of cell growth

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## The biological context

We consider a cross-diffusion system which describes a simplified model for contact inhibition of growth of two cell populations. In one space dimension it is known that the solutions satisfy a segregation property: if two populations initially have disjoint habitats, this property remains true at all later times.

Our purpose today : Extend this result to higher space dimension.

## Proliferation of cells

Two types of normal cells


Cell division


Proliferation stops!

## Proliferation of cancer cells

Two types of tumour cells


## Proliferation does not stop!

## Contact inhibition

## Here we consider a stage before the appearance of tumour cells.

## Normal cell

Abnormal cell

## Eventually tumour cells

## The model equations

This tumor growth model has been proposed by Chaplain, Graziano and Preziosi

$$
\begin{cases}n_{t}=\operatorname{div}(n \nabla V(N))+G_{n}(N) n & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ a_{t}=\operatorname{div}(a \nabla V(N))+G_{a}(N) a & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+}\end{cases}
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- n : density of normal cells;
- a: density of abnormal cells;
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## The model studied by Bertsch, Dal Passo and Mimura

Bertsch, Dal Passo and Mimura have proved the existence of a segregated solution of the system

$$
\left\{\begin{array}{l}
u_{t}=\operatorname{div}(u \nabla \chi(u+v))+u(1-u-\alpha v) \\
v_{t}=D \operatorname{div}(v \nabla \chi(u+v))+\gamma v(1-\beta u-v / k)
\end{array}\right.
$$

- u: density of normal cells;
in the one dimensional case. The growth terms are Lotka-Volterra competition terms.


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## The Bertsch, Dal Passo and Mimura result

More precisely, Bertsch, Dal Passo and Mimura have proved the existence of a segregated solution of the system

$$
\left\{\begin{array}{l}
u_{t}=\left(u(\chi(u+v))_{x}\right)_{x}+u(1-u-\alpha v) \quad-L<x<L, t>0 \\
v_{t}=D\left(v(\chi(u+v))_{x}\right)_{x}+\gamma v(1-\beta u-v / k) \quad-L<x<L, t>0 \\
\left.u(\chi(u+v))_{x}\right)=v(\chi(u+v))_{x}=0 \quad x=-L, L, t>0 \\
u(x, 0)=u_{0}(x), v(x, 0)=v_{0}(x),-L<x<L
\end{array}\right.
$$

The habitats of the two cell populations remain disjoint. Mathematically we express this property as follows If $u_{0} v_{0}=0$, then $u(t) v(t)=0$ for all $t>0$.

This system has the form of a nonlinear cross-diffusion system.

## The nonlinear cross-diffusion system

We suppose that $\chi=I d$ and $D=1$

$$
\left\{\begin{array}{l}
u_{t}=\frac{1}{2} \triangle u^{2}+u \triangle v+\nabla u . \nabla v+u(1-u-\alpha v), \\
v_{t}=\frac{D}{2} \triangle v^{2}+D v \triangle u+D \nabla u \cdot \nabla v+\gamma v(1-\beta u-v / k)
\end{array}\right.
$$

so that it is a hard system. This motivated Bertsch et al to look for other unknown functions. One of them is quite natural. We set

$$
w=u+v, w_{0}:=u_{0}+v_{0}
$$

and suppose that

$$
u_{0} \geq 0, v_{0} \geq 0, w_{0} \geq B_{0}>0
$$

Maximum principle type arguments successively tell that

$$
u(t) \geq 0, v(t) \geq 0, w(t) \geq B_{1}>0 \quad \text { for all } t>0
$$

## Regularity considerations

The equation for $w$ has the form of a nonlinear diffusion equation

$$
w_{t}=\operatorname{div}(w \nabla w)+w \mathcal{F}(u, v, w)
$$

This equation is uniformly parabolic since $w$ is bounded away from zero, and therefore $w$ is smooth. But now, suppose that $u$ and $v$ have disjoint supports. Then both $u$ and $v$ have to be discontinuous across the interface between their supports.

We are searching for discontinuous solutions $u$ and $v$ of the original system. This makes our problem very hard.

## A typical (u,v,w) profile


w is continuous and bounded away from zero. $u$ and $v$ are discontinuous at this point.

## Disjoint supports








## Overlapping supports








## New set of unknown functions

We set

$$
w:=u+v, r:=\frac{u}{u+v}
$$

and remark that in the case of disjoint supports, $r$ can only take the values 0 and 1, and that

$$
u v=0 \text { is equivalent to } r(1-r)=0
$$

The system for $w$ and $r$ is given by

$$
\begin{cases}w_{t}=\operatorname{div}(w \nabla w)+w F(r, w) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ r_{t}=\nabla w \cdot \nabla r+r(1-r) G(r, w) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ w(x, 0)=w_{0}(x) \text { and } r(x, 0)=r_{0}(x) & \text { for } x \in \mathbb{R}^{N}\end{cases}
$$

where

$$
\begin{aligned}
& F(r, w):=r(1-r w-\alpha(1-r) w)+\gamma(1-r)(1-\beta r w-(1-r) w / k) \\
& G(r, w):=(1-r w-\alpha(1-r) w)-\gamma(1-\beta r w-(1-r) w / k)
\end{aligned}
$$

## Regularity again

We deal with a coupled system with a parabolic equation for $w$ coupled to a transport equation for $r$. Now what can we expect for regularity? First consider the equation for $w$; applying again the maximum principle, we will have that $w$ is bounded from below by a positive constant whereas $0 \leq r \leq 1$. Therefore we can apply a very handy result of the book of Lieberman; this result is based upon regularity considerations such as in the elliptic articles of Agmon, Douglis, and Nirenberg. We obtain that $w$ is bounded in

$$
W_{p}^{2,1}\left(B_{L} \times(0, T)\right) \text { and in } C^{1+\mu,(1+\mu) / 2}\left(\bar{B}_{L} \times[0, T]\right)
$$

for all positive constants $L$, where $B_{L} \subset \mathbb{R}^{N}$ is the ball of radius $L$. In particular

$$
\nabla w \in C^{\mu, \mu / 2}\left(\bar{B}_{L} \times[0, T]\right)
$$

## The function $r$

We recall that it satisfies the first order hyperbolic equation

$$
r_{t}=\nabla w \cdot \nabla r+r(1-r) G(r, w) \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+}
$$

so that in particular

$$
0 \leq r \leq 1
$$

A possibility is to first solve the equations for the characteristics

$$
\left\{\begin{array}{l}
X_{t}(y, t)=-\nabla w(X(y, t), t) \text { for } t>0 \\
X(y, 0)=y \text { for } y \text { in } \mathbb{R}^{N}
\end{array}\right.
$$

and then solve for $R(y, t)=r(X(y, t), t)$ along the characteristics:

$$
\begin{cases}R_{t}=R(1-R) G(R, w(X(y, t), t)) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ R(\cdot, 0)=r_{0} & \text { in } \mathbb{R}^{N}\end{cases}
$$

## A regularity problem

However, since $\nabla w$ is not Lipschitz continuous, but only Hölder continuous, the characteristics are not well-defined in the classical sense. This is why we work with a recent concept of characteristics developed by DiPerna and Lions, De Lellis and Ambrosio.

More precisely, it permits to work with a velocity field $b=-\nabla w$ which only possess the "Sobolev regularity", namely

$$
b \in L_{\mathrm{loc}}^{\infty}\left(\mathbb{R}^{N} \times[0, \infty)\right) \cap L_{\mathrm{loc}}^{1}\left([0, \infty) ; W_{\mathrm{loc}}^{1,1}\left(\mathbb{R}^{N}\right)\right)
$$

## The main concepts of the survey paper by De Lellis

The starting point is a velocity field $b$ with the Sobolev regularity, namely

$$
b \in L_{\mathrm{loc}}^{\infty}\left(\mathbb{R}^{N} \times[0, \infty)\right) \cap L_{\mathrm{loc}}^{1}\left([0, \infty) ; W_{\mathrm{loc}}^{1,1}\left(\mathbb{R}^{N}\right)\right)
$$

We have here $b=-\nabla w$. Another new concept is that of a regular Lagrangian flow $\Phi$ satisfying

$$
\left\{\begin{array}{l}
\Phi_{t}(y, t)=-\nabla w(\Phi(y, t), t) \text { for } t>0 \\
\Phi(y, 0)=y \text { for } y \text { in } \mathbb{R}^{N}
\end{array}\right.
$$

We have here $\Phi=X$.

## Nearly incompressible vector field

A velocity field $b$ is said to be nearly incompressible if there exists a function $\eta \in L^{\infty}\left(\mathbb{R}^{N} \times[0, \infty)\right)$ and a positive constant $C$ such that $C \leq \eta \leq C^{-1}$ and

$$
\eta_{t}+\operatorname{div}(\eta b)=0
$$

in the sense of distributions. Here we will have $\eta=\rho$, with $\rho(x, t)=\mid \operatorname{det}\left(J^{-1}(x, t) \mid\right.$ and $J(y, t)$ the Jacobian matrix $\left\{\left(X_{i}\right)_{y_{j}}\right\}$.

## Concept of renormalized solutions

We say that the bounded nearly incompressible velocity field $b$ with density $\eta$ has the renormalization property if for all $c \in L_{\text {loc }}^{1}\left(\mathbb{R}^{N} \times[0, \infty)\right)$ and $q \in L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N} \times[0, \infty)\right)$ such that

$$
(q \eta)_{t}+\operatorname{div}(b \eta q)=c \eta
$$

in the sense of distributions, $\beta(q)$ satisfies

$$
(\beta(q) \eta)_{t}+\operatorname{div}(b \eta \beta(q))=c \eta \beta^{\prime}(q)
$$

in the sense of distributions for all $\beta \in C^{1}(\mathbb{R})$. This property, which is trivially satisfied if $c$ and $q$ are smooth functions, is nontrivial because of the regularity which is assumed here.
Any velocity field $b$ which possesses the "Sobolev regularity" satisfies the renormalization property.

## Regularization method

Our general approach is to work with smooth solutions, which are easy to work with, and then study their limit as the regularization parameter $n$ tends to infinity.

## Existence of smooth solutions on a bounded domain

Theorem. Let $\mathcal{B}_{n} \subset \mathbb{R}^{N}$ be a ball of radius $\mathcal{R}_{n}, \alpha, \beta, \gamma$ and $k$ positive constants, and $u_{0}, v_{0} \in C^{3}(\bar{\Omega})$ such that $u_{0}, v_{0} \geq 0$ and $u_{0}+v_{0} \geq B_{0}>0$ in $\Omega$. Then there exists a pair of smooth nonnegative solutions $(u, v)$, with $u, v \in C^{2,1}(\bar{\Omega} \times[0, T])$, of the problem

$$
\left(P_{n}\right) \begin{cases}u_{t}=\operatorname{div}(u \nabla(u+v))+u(1-u-\alpha v) & \text { in } \mathcal{B}_{n} \times \mathbb{R}^{+} \\ v_{t}=\operatorname{div}(v \nabla(u+v))+\gamma v(1-\beta u-v / k) & \text { in } \mathcal{B}_{n} \times \mathbb{R}^{+} \\ u \frac{\partial(u+v)}{\partial \nu}=v \frac{\partial(u+v)}{\partial \nu}=0 & \text { on } \partial \mathcal{B}_{n} \times \mathbb{R}^{+} \\ u(\cdot, 0)=u_{0}, v(\cdot, 0)=v_{0} & \text { in } \mathcal{B}_{n},\end{cases}
$$

where $\nu(x)$ denotes the outward normal at $x \in \mathcal{B}_{n}$.

## A remark

Note that $u$ and $v$ can be smooth since they are overlapping, first at the time $t=0$ and then at all later times.

## The corresponding approximating problem in $w$ and $r$

We recall that $w=u+v$ and that $r=u /(u+v)$. The problem then reads as

$$
\left(\mathcal{P}_{n}\right) \begin{cases}w_{t}=\operatorname{div}(w \nabla w)+w F(r, w) & \text { in } \mathcal{B}_{n} \\ r_{t}=\nabla w \cdot \nabla r+r(1-r) G(r, w) & \text { in } \mathcal{B}_{n} \\ w \frac{\partial w}{\partial \nu}=0 & \text { on } \partial \mathcal{B} \\ w(\cdot, 0)=w_{0}:=u_{0}+v_{0}, r(\cdot, 0)=r_{0}:=u_{0} / w_{0} & \text { in } \mathcal{B}_{n}\end{cases}
$$

## Existence of solution for the approximate problems

We define

$$
\mathcal{A}=\left\{r \in C^{\mu, \mu / 2}\left(\overline{\mathcal{B}}_{n} \times[0, T]\right), \quad 0 \leq r \leq 1\right\}
$$

For given $r \in C^{\mu, \mu / 2}\left(\overline{\mathcal{B}_{n}} \times[0, T]\right)$, let $w \in C^{2+\mu, 1+\mu / 2}\left(\overline{\mathcal{B}_{n}} \times[0, T]\right)$ be the unique solution of

$$
\begin{cases}w_{t}=\operatorname{div}(w \nabla w)+w F(r, w) & \text { in } \mathcal{B}_{n} \times(0, T] \\ w \frac{\partial w}{\partial \nu}=0 & \text { on } \partial \mathcal{B}_{n} \times(0, T] \\ w(\cdot, 0)=w_{0}:=u_{0}+v_{0} & \text { in } \mathcal{B}_{n} .\end{cases}
$$

An priori estimate of the form $0<B_{1} \leq w \leq B_{2}$ follows from the maximum principle.

## The equation on the characteristics

For given $w$, we consider the ODE for the characteristics

$$
\left\{\begin{array}{l}
X_{t}(y, t)=-\nabla w(X(y, t), t) \text { for } 0<t \leq T \\
X(y, 0)=y
\end{array}\right.
$$

Then $X$ is continuously differentiable and one to one from $\overline{\mathcal{B}}_{n} \times[0, T]$ into itself.
On the characteristics the transport equation reduces to the ODE

$$
\begin{cases}R_{t}=R(1-R) G(R, w(X(y, t), t)) & \text { in } \mathcal{B}_{n} \times(0, T] \\ R(\cdot, 0)=r_{0} & \text { in } \mathcal{B}_{n}\end{cases}
$$

The bounds on $w(x, t)$ and $X(y, t)$ imply that $R \in C^{1,1}\left(\overline{\mathcal{B}}_{n} \times[0, T]\right)$.

## Existence of a smooth solution

We transform $R(y, t)$ to the original variables:

$$
\tilde{r}(x, t):=R\left(X^{-1}(x, t), t\right) \quad \text { for }(x, t) \in \overline{\mathcal{B}}_{n} \times[0, T]
$$

and we find that $\tilde{r} \in C^{1,1}\left(\overline{\mathcal{B}}_{n} \times[0, T]\right)$.
We finally apply Schauder's fixed point theorem to the map $r \mapsto w \mapsto \tilde{r}=: \mathcal{T}(r)$ from the closed convex set $\mathcal{A}$ into itself and conclude that there exists a solution $\left(w_{n}, r_{n}\right)$ of $\operatorname{Problem}\left(\mathcal{P}_{n}\right)$.

## Existence of solution of the original system

We then return to the system

$$
\begin{cases}w_{t}=\operatorname{div}(w \nabla w)+w F(r, w) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ r_{t}=\nabla w \cdot \nabla r+r(1-r) G(r, w) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ w(x, 0)=w_{0}(x) \text { and } r(x, 0)=r_{0}(x) & \text { for } x \in \mathbb{R}^{N}\end{cases}
$$

and would like to prove that it possesses a solution. The main idea is to find a (weak) solution ( $w, r$ ) as a limit of a sequence of solutions $\left(w_{n}, r_{n}\right)$ of the problems $\left(\mathcal{P}_{n}\right)$.

## Technical difficulties

We have already seen that $\left\{w_{n}\right\}$ is bounded in $W_{p}^{2,1}\left(\mathcal{B}_{n} \times(0, T)\right)$. Therefore there exist a function $w \in W_{p, \text { loc }}^{2,1}\left(\mathbb{R}^{N} \times[0, \infty)\right)$ and a subsequence of $\left\{w_{n}\right\}$ which we denote again by $\left\{w_{n}\right\}$ such that

$$
w_{n} \rightarrow w \text { in } C_{\text {loc }}^{1+\mu,(1+\mu) / 2}\left(\mathbb{R}^{N} \times[0, \infty)\right) \text { as } n \rightarrow \infty
$$

On the other hand, we only know that

$$
0 \leq r_{n} \leq 1
$$

but nothing more; thus there exist $r \in[0,1]$ and a subsequence of $\left\{r_{n}\right\}$ which we denote again by $\left\{r_{n}\right\}$ such that

$$
r_{n} \rightharpoonup r \text { in } L_{l o c}^{2}\left(\mathbb{R}^{N} \times[0, \infty)\right) \text { as } n \rightarrow \infty
$$

At this point, we also know that there exists a bounded function $\chi$ such that

$$
F\left(r_{n}, w_{n}\right) \rightharpoonup \chi \text { as } n \rightarrow \infty
$$

but we do not know yet that $\chi=F(r, w)$.

## The essential result of Camillo De Lellis

Let $b$ a bounded nearly incompressible velocity field with the renormalization property. Then there exists a unique regular Lagrangian flow $\Phi$ for $b$. Moreover, let $b_{n}$ be a sequence of bounded nearly incompressible velocity fields with renormalization property such that
(i) $\left\{b_{n}\right\}$ is uniformly bounded in $L^{\infty}\left(\mathbb{R}^{N} \times(0, \infty) ; \mathbb{R}^{N}\right)$ and $b_{n} \rightarrow b$ strongly in $L_{\text {loc }}^{1}\left(\mathbb{R}^{N} \times(0, \infty) ; \mathbb{R}^{N}\right)$.

Then the regular Lagrangian flows $\Phi_{n}$ generated by $b_{n}$ converge to $\Phi$ in $L_{\mathrm{loc}}^{1}\left(\mathbb{R}^{N} \times(0, \infty) ; \mathbb{R}^{N}\right)$.
We recall that here $b=-\nabla w, \Phi=X$ and $\eta=\rho=\left|\operatorname{det}\left(J^{-1}\right)\right|$.

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(ii) The densities $\eta_{n}$ generated by $b_{n}$ satisfy $\lim \sup _{n}\left(\left\|\eta_{n}\right\|_{\infty}+\left\|\eta_{n}^{-1}\right\|_{\infty}\right)<\infty$.
Then the regular Lagrangian flows $\Phi_{n}$ generated by $b_{n}$ converge to $\Phi$ in $L_{\mathrm{loc}}^{1}\left(\mathbb{R}^{N} \times(0, \infty) ; \mathbb{R}^{N}\right)$.
We recall that here $b=-\nabla w, \Phi=X$ and $\eta=\rho=\left|\operatorname{det}\left(J^{-1}\right)\right|$.

## Strong convergence of $r_{n}$ to $r$

It follows from the theorem of De Lellis that

$$
X_{n} \rightarrow X \text { in } L_{l o c}^{1}\left(\mathbb{R}^{N} \times[0, \infty)\right) \text { as } n \rightarrow \infty
$$

Defining

$$
R_{n}(y, t)=r_{n}\left(X_{n}(y, t), t\right)
$$

we prove that

$$
R_{n} \rightarrow R \text { in } L_{l o c}^{1}\left(\mathbb{R}^{N} \times[0, \infty)\right)
$$

and also deduce that

$$
r_{n} \rightarrow r \text { in } L_{l o c}^{1}\left(\mathbb{R}^{N} \times[0, \infty)\right)
$$

## Segregation property

We consider again the equation for $R(y, t)=r(X(y, t), t)$. We recall that $r$ satisfies

$$
r_{t}=\nabla w \cdot \nabla r+r(1-r) G(r, w) \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+}
$$

so that $R$ is a solution of the problem

$$
\begin{cases}R_{t}=R(1-R) G(R, w(X(y, t), t)) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ R(y, 0)=r_{0}(y) & \text { for } y \in \mathbb{R}^{N} .\end{cases}
$$

In turn this implies that

$$
\begin{cases}(R(1-R))_{t}=R(1-R)(1-2 R) G(R, w(X(y, t), t)) & \text { in } \mathbb{R}^{N} \times \mathbb{R}^{+} \\ (R(1-R))(y, 0)=0 & \text { for } y \in \mathbb{R}^{N},\end{cases}
$$

so that

$$
R(1-R)=0 \text { or else } u v=0 \in \mathbb{R}^{N} \times \mathbb{R}^{+} .
$$

## Singular limit in a special case

We consider the special case that $\alpha=1$ and that $\beta=\frac{1}{k}$ and consider the corresponding problem on a bounded domain with natural boundary conditions. This gives

$$
\begin{cases}u_{t}=\operatorname{div}(u \nabla(u+v))+(1-u-v) u, & \\ v_{t}=\operatorname{div}(v \nabla(u+v))+\gamma\left(1-\frac{u+v}{k}\right) v, & x \in \Omega, t \in(0, T], \\ u \nabla(u+v) \cdot \nu=0, & x \in \partial \Omega, t \in(0, T], \\ v \nabla(u+v) \cdot \nu=0, & x \in \Omega, \\ u(x, 0)=u_{0}(x), & \\ v(x, 0)=v_{0}(x), & \end{cases}
$$

where $\nu$ is a outward normal unit vector, and we we set $w=u+v$.

## Singular limit in a special case

The system for $w$ and $v$ is given by

$$
\left\{\begin{array}{lc}
w_{t}=\operatorname{div}(w \nabla w)+(1-w) w+(\gamma(1-\kappa w)-1-w) v & \text { in } \Omega \times(0, T] \\
v_{t}=\operatorname{div}(v \nabla w)+\gamma(1-\kappa w) v & \text { in } \Omega \times(0, T] \\
w \nabla w \cdot \nu=v \nabla w \cdot \nu=0 & \text { on } \partial \Omega \times(0, T] \\
w(x, 0)=w_{0}(x), v(x, 0)=v_{0}(x), & x \in \Omega
\end{array}\right.
$$

where $\kappa=k^{-1}$. This problem is easier to study since the reaction terms are linear in $v$.

## The uniformly parabolic approximating problem

In order to prove the existence of a solution, we can approximate it by a uniformly parabolic system, say

$$
\left\{\begin{array}{lr}
w_{t}=\varepsilon \Delta w+\operatorname{div}(w \nabla w)+(1-w) w+(\gamma(1-\kappa w)-1-w) v & \text { in } Q_{T}, \\
v_{t}=\varepsilon \Delta v+\operatorname{div}(v \nabla w)+\gamma(1-\kappa w) v & \text { in } Q_{T}, \\
w \nabla w \cdot \nu=v \nabla w \cdot \nu=0 & \text { on } \partial \Omega \times(0, T], \\
w(x, 0)=w_{0}(x), v(x, 0)=v_{0}(x), & x \in \Omega
\end{array}\right.
$$

where $Q_{T}=\Omega \times(0, T]$, and find that along a subsequence as $\varepsilon \rightarrow 0$
$w^{\varepsilon} \rightarrow w$ strongly in $L^{2}\left(Q_{T}\right)$,
$\nabla w^{\varepsilon} \rightharpoonup \nabla w$ weakly in $L^{2}\left(Q_{T}\right)$,
$v^{\varepsilon} \rightharpoonup v$ weakly in $L^{2}\left(Q_{T}\right)$,
where $(w, v)$ is a solution of the original problem.

## The convergence result

Theorem. As $k$ tends to zero, $v^{k}$ converges to zero weakly in $L^{2}\left(Q_{T}\right)$, and $w^{k}$ converges strongly in $L^{2}\left(Q_{T}\right)$ to the unique weak solution $u$ of the problem

$$
\left\{\begin{array}{lr}
u_{t}=\operatorname{div}(u \nabla u)+(1-u) u & \text { in } Q_{T}, \\
u \nabla u \cdot \nu=0 & \text { on } \partial \Omega \times(0, T], \\
u(x, 0)=u_{0}(x) & x \in \Omega .
\end{array}\right.
$$

